

## COURSE OUTLINE: RAA112 - APP OF RBT W/ SOLID

Prepared: Donovan Kennedy

Approved: Corey Meunier, Chair, Technology and Skilled Trades

Course Code: Title	RAA112: APPLICATIONS OF ROBOTICS/SOLID MODELING		
Program Number: Name	4073: ROBOTICS & AUTOMATIO		
Department:	ROBOTICS GRADUATE CERTIFICATE		
Semesters/Terms:	20F		
Course Description:	The purpose of this course is to familiarize students with solid modeling, parametric design application used for Mechanical/Industrial and Robotic solid design. The course is designed to provide students with an experiential learning environment through a process or task based approach to learning the individual features and functions of solid modeling software, thereby emphasizing processes and procedures for design for robotics. The course begins with an overview of the parametric 2D design environment and progresses to solids and assemblies. Advanced features of the software including top down and bottom design will be covered with a strong emphasis on design for robotic applications. Students attending this course are expected to have experience with computers and Windows operating system. Knowledge of the principles of drafting and design and is expected.		
Total Credits:	3		
Hours/Week:	2		
Total Hours:	30		
Prerequisites:	There are no pre-requisites for this course.		
Corequisites:	There are no co-requisites for this course.		
This course is a pre-requisite for:	RAA204		
Vocational Learning Outcomes (VLO's) addressed in this course:	4073 - ROBOTICS & AUTOMATIO  VLO 1 Construct and evaluate robotic control programs for various scenarios against which to model the functionality and stability of automation systems.		
Please refer to program web page for a complete listing of program outcomes where applicable.	VLO 6 Integrate budgetary, technical, functional and safety considerations in the design and optimization of custom automation solutions.		
	VLO 7 Formulate and use a variety of troubleshooting techniques on new and legacy electromechanical equipment, processes, systems and subsystems.		
Essential Employability Skills (EES) addressed in	EES 1 Communicate clearly, concisely and correctly in the written, spoken, and visual form that fulfills the purpose and meets the needs of the audience.		
this course:	EES 2 Respond to written, spoken, or visual messages in a manner that ensures effective communication.		
	EES 3 Execute mathematical operations accurately.		
	EES 4 Apply a systematic approach to solve problems.		
	EES 5 Use a variety of thinking skills to anticipate and solve problems.		

In response to public health requirements pertaining to the COVID19 pandemic, course delivery and assessment traditionally delivered in-class, may occur remotely either in whole or in part in the 2020-2021 academic year.



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RAA112: APPLICATIONS OF ROBOTICS/SOLID MODELING

	EES 6	Locate, select, orga	nize, and document information using appropriate technology tems.	
	EES 7	Analyze, evaluate,	and apply relevant information from a variety of sources.	
	EES 9		in groups or teams that contribute to effective working e achievement of goals.	
	EES 10	Manage the use of	time and other resources to complete projects.	
	EES 11	Take responsibility	for ones own actions, decisions, and consequences.	
Course Evaluation:	Passing Grade: 50%, D			
	A minimum program GPA of 2.0 or higher where program specific standards exist is required for graduation.			
Other Course Evaluation & Assessment Requirements:				
	It is the departmental policy that once the classroom door has been closed, the learning process has begun. Late arrivers will not be granted admission to the room.			
Course Outcomes and	Course	Outcome 1	Learning Objectives for Course Outcome 1	
Learning Objectives:	Two Dimensional     Sketching	Potential Elements of the Performance:		
		1.1 Establish Sketch Planes		
			1.2 2D Constraints	
			1.3 Parametric Dimensions	
	Course	Outcome 2	Learning Objectives for Course Outcome 2	

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2. Revolved and Extruded

Features



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Potential Elements of the Performance:

	2.1 Extrude Solid Parts From Sketches 2.2 Revolve Solid Parts from Sketches 2.3 Cut-outs from Parts using Extrusions 2.4 Revolved Cuts from Parts using Revolutions 2.5 Establishing Planes for Features
Course Outcome 3	Learning Objectives for Course Outcome 3
3. Holes and Patterns	Potential Elements of the Performance:
	3.1 How to Use Hole and Thread Features 3.2 How to use Patterns to Create Multiple Features
Course Outcome 4	Learning Objectives for Course Outcome 4
4. Assemblies	Potential Elements of the Performance:
	<ul><li>4.1 Create Assemblies</li><li>4.2 Understand Assembly Constraints</li><li>4.3 Bottom-up design</li><li>4.4 Top-down design</li></ul>
Course Outcome 5	Learning Objectives for Course Outcome 5
5. Drawings from 3D Models and Assemblies	Potential Elements of the Performance: 5.1 Placing Principle Orthographic Views 5.2 Placement of Dimensions 5.3 BOM tables and automatic population
Course Outcome 6	Learning Objectives for Course Outcome 6
6. Advantages of Solid Modeling	Potential Elements of the Performance:  6.1 Mass Property Analysis 6.2 Check Interference 6.3 Linked Parts and Assemblies 6.4 Editing and Modifying Parts and Assemblies 6.5 Motion Study

## **Evaluation Process and Grading System:**

<b>Evaluation Type</b>	<b>Evaluation Weight</b>
Assignments	70%
Attendance	10%
Final Exam	20%

Date:

June 11, 2020

Addendum:

Please refer to the course outline addendum on the Learning Management System for further information.

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